

ERRATA

Colaço, A. F. **Mobile terrestrial laser scanner for site-specific management in orange crop.** Piracicaba, 2016. 87 p. Tese (Doutorado) - Escola Superior de Agricultura "Luiz de Queiroz", Universidade de São Paulo, Piracicaba, 2016.

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22	Figura 2.9	Reconstruction algorithms applied over 3D point clouds; hull structure (b) created over sections of a point cloud from an apple tree (a), adapted from Rosell et al. (2009b); convex-hull (d) applied over point cloud from an olive tree (c)	Reconstruction algorithms applied over 3D point clouds. Hull structure (b) created over sections of a point cloud from an apple tree (a), adapted from Rosell et al. (2009b). Convex hull (d) applied over point cloud from an olive tree (c), adapted from Auat Cheein and Guivant (2014). Convex hull, α hull, and cylinder fit (e) reconstruction
40	2	R software	R 3.2.2 software
42	3	CloudCompare	CloudCompare 2.6.1
43	15	CloudCompare	CloudCompare 2.6.1
43	25	CloudCompare	CloudCompare 2.6.1
47	11	showed	shown
48	Figura 3.13	classification	classification
51	2	showed	shown
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65	14	QGIS	QGIS 2.10
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